

# FEniCS - very short introduction

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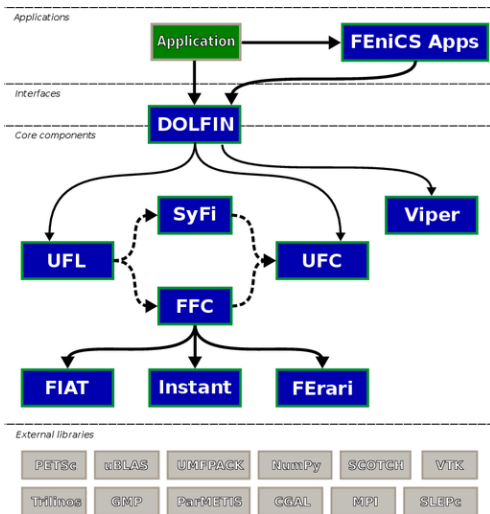


## Automated Solution of Differential Equations by the Finite Element Method

- ▶ started in 2003, collaboration between University of Chicago and Chalmers University of Technology
- ▶ end of 2011 - version 1.0, tutorial book published (jan 2012) with main contribution by 5 institutions (Simula Research Laboratory, University of Cambridge, University of Chicago, Texas Tech University, KTH Royal Institute of Technology)
- ▶ open source license (GNU LGPL v3)
- ▶ development on launchpad (<https://launchpad.net/fenics-project>)

- info:**
- ▶ FEniCS book - Volume 84 of the Springer Lecture Notes in Computational Science and Engineering
  - ▶ preliminary version of the book <https://launchpad.net/fenics-book>
  - ▶ official tutorial <http://fenicsproject.org/documentation/tutorial>

- ▶ core components:
  - Dolfin** C++/Python interface of FEniCS, providing a consistent Problem Solving Environment
  - FFC** FEniCS Form Compiler - compiler for multilinear forms by generating code (C++)
  - FIAT** Finite element Automatic Tabulator (currently Lagrange, mixed FE)
  - Instant** Python module that allows for instant inlining of C and C++ code in Python
  - UFC** Unified Form-assembly Code is a unified framework for finite element assembly
  - UFL** Unified Form Language is specific language for declaration of finite element discretizations of variational forms
- ▶ additional libraries: Dorsal, FErari, SyFi, Viper
- ▶ external libraries: PETSc, UMFPACK, Trilinos, CGAL, VTK,....



$$\operatorname{div} \operatorname{grad} u = f \quad \text{in } \Omega = [0, 1] \times [0, 1] \quad (1)$$

$$u = 0 \quad \text{on } \partial\Omega \quad (2)$$

```
from dolfin import *

mesh = UnitSquare(32, 32)
V = FunctionSpace(mesh, "Lagrange", 1)

u0 = Constant(0.0)
bc = DirichletBC(V, u0, DomainBoundary())

u = TrialFunction(V)
v = TestFunction(V)
f = Expression("x[0]+x[1]")

a = inner(grad(u), grad(v))*dx
L = f*v*dx

u = Function(V)
solve(a == L, u, bc)
```

## ► use iterative solver:

```
prm = parameters['krylov_solver'] # short form
prm['absolute_tolerance'] = 1E-10
prm['relative_tolerance'] = 1E-6
prm['maximum_iterations'] = 1000
set_log_level(PROGRESS)

solve(a == L, u, bc,
      solver_parameters={'linear_solver': 'cg',
                        'preconditioner': 'ilu'})
```

## ► nonlinear solver

```
u = Function(V)
v = TestFunction(V)

F = inner((1.0+u**2)*grad(u), grad(v))*dx - f*v*dx
# jacobian can be computed by ... J = derivative(F, u_, u)

solve(F == 0, u, bc,
      solver_parameters={"newton_solver":
                        {"relative_tolerance": 1e-6}})
```